ECE 587 – Hardware/Software Co-Design Lecture 08 Concurrency in Practice II

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- This lecture: Memory Ordering
- Next lectures: RISC-V and Chipyard

## Outline

#### Memory Ordering

Memory Barrier

### **Observable State Transitions**

- We assume each process in a process-based model is specified by a state-based model, e.g. a sequential program.
- For shared memory communication, processes react by observing changes in the shared states.
  - It is possible to implement shared memory communication on top of message passing and vice versa.
  - So here we refer to the shared memory communication as is.
- Are the observed state transitions the same as the state-based model specify in practice?
  - State bits that are not observable (from the shared memory).
  - Missing transitions.
  - Reordered transitions.
- Let's look at multi-threaded programs on multi-core processors.

- Each processor core can issue an instruction per clock cycle: fraction of a nano-second (ns).
- Memory access latency: about 10 ns
- There must be optimizations or the core has to wait for memory.
  - Compiler
  - Micro-architecture
  - Cache

# Compiler Optimization

#### Registers

- Once a variable is available from a register, there is no need to read it from the memory.
- A variable in a register need to be written to the memory only if the register need to be used for another variable.
- Registers are not observable from other processes.
- Operations can be reordered as long as there is no data or control dependency.

Think of DFG.

- If the above are true for any single process, what about observed state transitions?
  - Is it possible/correct for a variable to stay only in the register?
  - Is it possible/correct for a variable to have two different values, one in the register and one in the memory?

## Micro-Architecture

- While a core may issue an instruction per cycle, the instruction may take several cycles to complete.
  - Lengthy computations.
  - Wait for data to be available from memory.
- Out-Of-Order (OOO) execution
  - Allow later instructions to execute as long as there is no data/control dependencies.
  - A load/store buffer is usually necessary to buffer memory writes and to forward memory reads for better performance.
  - Re-order buffer (ROB) helps to commit intructions in order, giving the illusion that they are executed in order.
- Out-Of-Order memory updates
  - After the instruction is committed, for correctness on a single core, it doesn't matter when the load/store buffer actually updates the memory.
  - Similar effects as compiler optimization.

- Cache brings data closer to the processor core.
  - No need to go to (main) memory if the data is available from the cache.
- There are multiple copies of the same data in the memory hierarchy.
  - Main memory.
  - Multiple levels of cache.
  - If there are many cores, each core may have its own cache.
  - ► The load/store buffer on each core.

# Cache Coherence

- Ensure cores to have consensus on the value of a particular memory location.
- MESI protocol
  - State-based, each core maintain a FSM per cache line.
  - 4 states: Modified, Exclusive, Shared, Invalid
  - Shared read or exclusive write per cache line.
- If the variable fits into a cache line, then writes/reads to it are ordered sequentially across cores, though not deterministic.
- Contention happens when many cores attempt to update the same cache line simultaneously.

### When Intuition Fails ...

Core 1	Core 2
data = 100; ready = 1;	<pre>while (ready == 0)     wait_a_while();     print(data);</pre>

- Assume initially ready=0 and data=0.
- What could happen?
  - Assume a cache coherence protocol is used.
  - Does it matter if you turn on/off compiler optimizations?

# Outline

Memory Ordering

Memory Barrier

 Cache coherence ensures ordering of memory access to the same memory location (cache line).

But not to *multiple* memory locations.

- Memory barriers provide guarantees of ordering among accesses to *multiple* memory locations.
- ► A joint effort of compiler and core micro-architecture.
  - Need language support to guide compiler optimization.
  - Compiler further translates them into corresponding special instructions that force updates in the memory hierarchy.

### Example: Use a Channel

```
int main() {
  channel<std::string> chan;
  std::thread p([&] {
    chan.put("hello");
    chan.put("world");
  });
  std::thread c([&] {
    printf("%s\n", chan.get().c_str());
    printf("%s\n", chan.get().c_str());
  });
  p.join(); c.join();
  return 0;
}
```

Message passing via channel.

How to implement the channel via shared memory?

# A Simple Channel Implementation

```
template <class T>
class channel {
   std::atomic<bool> empty_;
   T val_;
public:
   channel() {
    empty_.store(true, std::memory_order_relaxed);
   }
   ...
}; // class channel<T>
```

- std::memory\_order\_relaxed prevents any compiler optimization and ensures atomic updates.
- Thread creation works as full memory barrier so both threads will see empty\_ as true initially.

# A Simple Channel Implementation (Cont.)

```
template <class T>
class channel {
  . . .
  T get() {
    while (empty_.load(std::memory_order_acquire))
    T ret = val :
    empty_.store(true, std::memory_order_release);
    return ret;
  }
  void put(const T &val) {
    while (!empty_.load(std::memory_order_acquire))
    val_ = val;
    empty_.store(false, std::memory_order_release);
  }
}: // class channel<T>
```

store with std::memory\_order\_release pairs with load with memory\_order\_acquire.

Prevent compiler optimization.

Preceding stores will be seen by loads afterwards.

#### Discussions

- Memory barriers usually work in pairs to establish the so-called *happens-before* relations to ensure visibility of memory updates.
- There are memory barriers other than the release-acquire pair, depending on processor architectures.
- OS synchronizations (thread creation, lock, etc.) work as full memory barrier where all ordering with reference to them are preserved across all threads.
- When contention is low, since our channel doesn't use any OS synchronization that may potentially suspend the thread, the communication latency could be very small.
- How to implement a channel that can hold more than one token, or can support multiple producers?

- ► Java Concurrency in Practice, Goetz et al., 2006.
- ► C++ Concurrency in Action, Williams, 2012.
- Is Parallel Programming Hard, And, If So, What Can You Do About It? https://www.kernel.org/pub/linux/kernel/people/ paulmck/perfbook/perfbook.html