

ECE 473/573
Cloud Computing and Cloud Native Systems
Lecture 16 Resource Management II

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Borg

Reading Assignment

- ▶ This lecture: Large-scale cluster management at Google with Borg <https://storage.googleapis.com/pub-tools-public-publication-data/pdf/43438.pdf>
- ▶ Next lecture: Kubernetes <https://kubernetes.io/docs/concepts/>

Borg

Google Borg

- ▶ An internal cluster management system developed by Google.
 - ▶ Across a number of clusters each with up to tens of thousands of machines.
 - ▶ Support hundreds of thousands of jobs from many thousands of different applications.
- ▶ Benefits
 - ▶ Hide details of resource management and failure handling so users can focus on application development.
 - ▶ High availability and reliability, and support applications that do the same.
 - ▶ Operating at scale while providing resiliency and completeness.

User Perspective

- ▶ Users of Borg are developers and SREs (system administrators as site reliability engineers).
- ▶ Unit of management is a Borg cell.
 - ▶ Users submit work to Borg as jobs.
 - ▶ Each job consists of tasks all run the same binary program.
 - ▶ The Borg cell refers to the set of machine the job runs in.
- ▶ Physically, machines in a cell belong to a single cluster.
 - ▶ In a single datacenter building, connected by high-performance datacenter-scale network.
 - ▶ Machines are heterogeneous: CPU etc. can be all different.
- ▶ Borg manages physical machines and hides their differences and failures from users.
 - ▶ Install programs and dependencies.
 - ▶ Health monitoring.
 - ▶ Restart failed machines.

Workloads

- ▶ End-user-facing services.
 - ▶ Sensitive to latency.
 - ▶ Usually short-lived: us to sub-second
- ▶ Batch jobs.
 - ▶ Take longer time to complete: seconds to days
 - ▶ Not sensitive to short-term performance fluctuations.
- ▶ The workload mix varies across applications and over time.

Job and Task Management

- ▶ Each job has a name, an owner, and the number of tasks.
- ▶ Each job can in addition have constraints.
 - ▶ Force its tasks to run on machines with particular attributes like processor type and OS version.
 - ▶ Hard constraints must be satisfied; soft one are preferences.
- ▶ Each task maps to a set of Linux processes running in a container on a machine.
 - ▶ Task specifies its resource requirement.
 - ▶ Task also knows its index within the job.
- ▶ Jobs and tasks in the system are in one of the three states: Pending, Running, Dead.
 - ▶ Users can submit new jobs or resubmit Dead jobs, which move into Pending state if accepted.
 - ▶ Users can kill Pending and Running jobs into Dead state.
 - ▶ Users can update Pending and Running jobs without interrupting them.
 - ▶ Borg takes care of the rest, e.g. to schedule a Pending job into Running state, and move jobs to Dead for failures.

Quota and Priority

- ▶ Each job has a priority.
 - ▶ Express the relative importance of jobs.
 - ▶ e.g. monitoring > production > batch > best effort
- ▶ Quota is used to decide which jobs to admit for scheduling.
 - ▶ A vector of maximum resource usage for a period of time (typically months) at a given priority for an user.
 - ▶ e.g. 20TB of memory for production for the rest of the month.
 - ▶ Jobs with insufficient quota are rejected upon submission.
- ▶ Once admitted, higher priority jobs may preempt lower priority ones to obtain resources.
- ▶ Higher priority quota is limited to available resources.
 - ▶ However, users tend to overbuy higher priority quota to avoid future shortages – waste of resource!
 - ▶ Quota for lowest priority is set to infinite for all users.
 - ▶ Jobs of lower priorities may be admitted but need to wait resources to become available.

Naming and Monitoring

- ▶ A “Borg name service” (BNS) name allows to identify a task via the cell name, job name, and task index.
 - ▶ The BNS name is further used in the DNS name for the task.
- ▶ Almost every task uses its own HTTP server to report its health and performance metrics.
 - ▶ Borg restarts a task if its HTTP server stops to respond.
 - ▶ Monitoring tools track these data for visualization and notifications.

Borg Architecture

- ▶ Recall that for each job there will be a Borg cell which includes all machines the job runs on.
- ▶ Each Borg cell has a controller named Borgmaster.
 - ▶ Consist of two processes: the main Borgmaster process and a separate scheduler.
- ▶ Borglet, an agent process, runs on each machine in the cell.
 - ▶ Start, stop, restart tasks and manage local resources.
- ▶ The Borgmaster main process interfaces with users and Borglets, and manages states for tasks and machines.
 - ▶ With multiple replicas supported by Paxos consensus.
 - ▶ These replicas stores checkpoints, which consist of state snapshots and change logs at a point in time.
 - ▶ Checkpoints are used for fault recovery, troubleshooting, offline simulation etc.

Scheduling

- ▶ Once a job is accepted by the Borgmaster main process, its tasks are queued for scheduling by the scheduler.
- ▶ The scheduler needs to evaluate task-machine relationships to schedule tasks to machines.
- ▶ Feasibility checking: a task is feasible to run on a machine if there are sufficient available resources.
 - ▶ Plus additional constraints from the job.
 - ▶ May consider to evict lower-priority tasks.
- ▶ Scoring: decide which tasks to run if many are feasible and decide where to run them.
 - ▶ Consider priority and fairness, data and package availability, power and failure domains, packing quality for load spike etc.

Optimizations for Scalability

- ▶ Functional partitioning: use separate threads for Boglet to Borgmaster communications and read-only queries.
 - ▶ Sharding further distributes these works to replicas.
- ▶ Score caching: recompute scores for tasks and machines only when there are changes.
- ▶ Equivalence classes: handle similar tasks in a job as a whole so that feasibility checking and scoring only need to run once.
- ▶ Relaxed randomization: for a single task, avoid to evaluate it on all machines for feasibility checking and and scoring.
 - ▶ If enough machines evaluated following a random order are feasible, then the best score so far is good enough.

Techniques for Availability

- ▶ Keep tasks running even if Borgmaster or Boglets are down.
- ▶ Automatically reschedule evicted tasks
 - ▶ Reduce correlated failures by spreading tasks of a job across failure domains such as machines, racks, and power domains.
 - ▶ Rate-limit to find new machines for tasks as it could be either due to large-scale machine failure or network partitioning.
 - ▶ Avoid repeating task-machine schedulings that lead to crash.
- ▶ Limit task disruptions within a job during maintenance.
- ▶ Use idempotent operations to support retries.

Isolation

- ▶ Security isolation is achieved by a combination of Linux chroot jail, cgroup (container), and VM for software from various sources.
- ▶ Performance isolation is supported via containers.
 - ▶ In order to limit resource usages of tasks.
 - ▶ Use appclass to indicate needs of tasks: latency-sensitive vs batch.
 - ▶ Separate compressible resources like CPU and I/O bandwidth, from non-compressible resources like memory capacity.
 - ▶ Compressible resources can be reclaimed by rate-limiting.
 - ▶ Kill tasks requiring more non-compressible resources than allowed, or when such resources are over-committed.
 - ▶ Improve standard Linux CPU scheduler for both low latency and high utilization.

Summary

- ▶ People learned a lot from building Borg to support cluster computing needs in Google, which are eventually applied in the development of Kubernetes.